The Re-nonnegative definite solutions to the matrix equation AXB = C

QINGWEN WANG, CHANGLAN YANG

Abstract. An $n \times n$ complex matrix A is called Re-nonnegative definite (Re-nnd) if the real part of x^*Ax is nonnegative for every complex n-vector x. In this paper criteria for a partitioned matrix to be Re-nnd are given. A necessary and sufficient condition for the existence of and an expression for the Re-nnd solutions of the matrix equation AXB = C are presented.

Keywords: Re-nonnegative define matrix, matrix equation, generalized singular value decomposition

Classification: 15A24, 15A57

In 1996, Lei Wu and Bryan Cain [1] defined a Re-nonnegative definite (Re-nnd) matrix (that is, $A \in \mathbb{C}^{n \times n}$ is called Re-nnd if $Re[x^*Ax] \geq 0$ for every nonzero x in $\mathbb{C}^{n \times 1}$), presented a criterion for Re-nndness, and solved the matrix inverse problem: Given complex matrices X and B, find the set of all complex Re-nnd matrices A such that AX = B. It is well known that the matrix equation

$$AXB = C,$$

where A, B, C are given and X is unknown, is very important; it was investigated by C.G. Khatri and S.K. Mitra [2], K.E. Chu [3], A.D. Porter and N. Mousouris [4], D. Hua [5], Q.W. Wang [6]–[8] and others. In this paper we extend the results of [1], give criteria for 2×2 and 3×3 partitioned matrices to be Re-nnd, derive a necessary and sufficient condition for the existence of and an expression for Re-nnd solutions of the equation (1). Throughout this paper, \mathbb{C} , $\mathbb{C}^{m \times n}$, $\mathbb{C}^{m \times n}$, GL_n , E^n will represent the complex field, the set of all $m \times n$ matrices over \mathbb{C} , the set of all matrices in $\mathbb{C}^{m \times n}$ with rank r, the set of all $n \times n$ invertible matrices and the set of all $n \times n$ Re-nnd matrices, respectively. A^* , rank A, Re[b] and I_i will denote the conjugate transpose of a complex matrix A, the rank of A, the real part of a complex number b, and $i \times i$ identity matrix, respectively. $H(A) = \frac{1}{2}(A^* + A)$, $P^{-*} = (P^*)^{-1} = (P^{-1})^*$.

Project supported by NSF of Shandong & China.

2. Criteria for partitioned matrices to be Re-nnd

In this section, we improve a result concerning Re-nndness, and give a criterion for 3×3 matrix to be Re-nnd.

Lemma 1 ([1]). $A \in E^n$ iff H(A) is nonnegative definite (abbreviated nnd).

Extending Lemma 2 in [1], we have the following

Lemma 2. Let a Hermitian matrix A be partitioned as

$$A = \begin{bmatrix} A_{11} & A_{12} \\ A_{12}^* & A_{22} \end{bmatrix},$$

where A_{11} and A_{22} are Hermitian submatrices. Then the following conditions are equivalent:

- (i) A is nnd;
- (ii) rank $[A_{11}, A_{12}] = \text{rank } A_{11}$, both A_{11} and $A_{22} U^* A_{11} U$ are nnd where U is an arbitrary but fixed solution of the matrix equation $A_{11}X = A_{12}$ for X;
- (iii) rank $[A_{12}^*, A_{22}]$ = rank A_{22} , both A_{22} and $A_{11} U^*A_{22}U$ are nnd where U is an arbitrary but fixed solution of $A_{22}X = A_{12}^*$ for X.

Theorem 1. Suppose

$$A = \begin{pmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{pmatrix} \in \mathbb{C}^{n \times n}$$

where $A_{ii} \in \mathbb{C}^{n_i \times n_i}$ $(n_1 + n_2 = n)$. Then the following statements are equivalent:

- (i) $A \in E^n$;
- (ii) $\operatorname{rank}(A_{11} + A_{11}^*) = \operatorname{rank}[A_{11} + A_{11}^*, A_{12} + A_{21}^*]$, both A_{11} and $A_{22} U^*A_{11}U$ are Re-nnd, where U is an arbitrary but fixed solution of the matrix equation

$$(A_{11} + A_{11}^*)X = A_{12} + A_{21}^*$$

for X;

(iii) rank $(A_{22} + A_{22}^*)$ = rank $(A_{12}^* + A_{21}, A_{22} + A_{22}^*)$, both A_{22} and $A_{11} - U^*A_{22}U$ are Re-nnd, where U is an arbitrary solution of the matrix equation

$$(A_{22} + A_{22}^*)X = A_{12}^* + A_{21}$$

for X.

PROOF: Note that

$$2H(A) = \begin{pmatrix} A_{11} + A_{11}^* & A_{12} + A_{21}^* \\ A_{21} + A_{12}^* & A_{22} + A_{22}^* \end{pmatrix},$$

 $2H(A_{22}) = A_{22} + A_{22}^*, \ 2H(A_{11} - U^*A_{22}U) = A_{11} + A_{11}^* - U^*(A_{22} + A_{22}^*)U.$ By Lemma 1 and Lemma 2, (i) \Leftrightarrow (iii).

Similarly, (i) \Leftrightarrow (ii) may be proved.

Lemma 3. Let

$$A = \begin{pmatrix} A_{11} & A_{21}^* & X_{31}^* \\ A_{21} & A_{22} & A_{32}^* \\ X_{31} & A_{32} & A_{33} \end{pmatrix} \begin{array}{c} r_1 \\ r_2 \\ n - r_1 - r_2 \end{array}$$

be Hermitian. Then there exists $X_{31} \in \mathbb{C}^{(n-r_1-r_2)\times r_1}$ such that A is nnd if and only if both

$$\begin{pmatrix} A_{11} & A_{12}^* \\ A_{21} & A_{22} \end{pmatrix}$$
 and $\begin{pmatrix} A_{22} & A_{32}^* \\ A_{32} & A_{33} \end{pmatrix}$

are nnd.

PROOF: "Necessity" is obvious by Lemma 2. Now we prove the "Sufficiency". By Lemma 2, we may assume that U_1 (respectively U_2) is an arbitrary solution of $A_{22}X = A_{21}$ (respectively $A_{33}X = A_{32}$) for X. Taking $X_{31} = A_{32}U_1$ and

$$P = \begin{pmatrix} I_{r_1} & O & O \\ -U_1 & I_{r_2} & O \\ O & -U_2 & I_{n-r_1-r_2} \end{pmatrix},$$

we get that

$$P^*AP = \operatorname{diag}(A_{11} - U_1^* A_{22} U_1, A_{22} - U_2^* A_{33} U_2, A_{33}).$$

By Lemma 2, A is nnd.

Theorem 2. Suppose

$$A = \begin{pmatrix} A_{11} & A_{12} & A_{13} \\ A_{21} & A_{22} & A_{23} \\ X_{31} & A_{32} & A_{33} \end{pmatrix} \begin{matrix} r_1 \\ r_2 \\ n-r_1-r_2 \end{matrix} \in \mathbb{C}^{n \times n}.$$

Then there exists $X_{31} \in \mathbb{C}^{(n-r_1-r_2)\times r_1}$ such that $A \in E^n$ if and only if

$$A_1 = \begin{pmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{pmatrix} \in E^{r_1 + r_2}, \quad A_2 = \begin{pmatrix} A_{22} & A_{23} \\ A_{32} & A_{33} \end{pmatrix} \in E^{n - r_1}.$$

PROOF: Assume $B_{11} = A_{11} + A_{11}^*$, $B_{21} = A_{21} + A_{12}^*$, $B_{31} = X_{31} + A_{13}^*$, $B_{22} = A_{22} + A_{22}^*$, $B_{32} = A_{32} + A_{23}^*$, $B_{33} = A_{33} + A_{33}^*$. Then

$$2H(A_1) = \begin{pmatrix} B_{11} & B_{21}^* \\ B_{21} & B_{22} \end{pmatrix}, \quad 2H(A_2) = \begin{pmatrix} B_{22} & B_{32}^* \\ B_{32} & B_{33} \end{pmatrix},$$
$$2H(A) = \begin{pmatrix} B_{11} & B_{21}^* & B_{31}^* \\ B_{21} & B_{22} & B_{32}^* \\ B_{31} & B_{32} & B_{33} \end{pmatrix}.$$

Hence, the theorem follows immediately from Lemma 3 and Lemma 1. \Box

3. Re-nnd solutions to the matrix equation (1)

Now we consider the Re-nnd solutions of (1) where $A \in \mathbb{C}^{m \times n}$, $B \in \mathbb{C}^{n \times q}$, $C \in \mathbb{C}^{m \times q}$ are given and $X \in \mathbb{C}^{n \times n}$ is unknown.

We decompose the matrices A and B^* using the generalized singular value decomposition (GSVD) [9]

(2)
$$UAP = \left[\sum_{k} O_{n-k}\right], \quad VB^*P = \left[\sum_{k} O_{n-k}\right],$$

where

(3)
$$\sum_{A} = \begin{pmatrix} I_r & \\ & S_A & \\ & O \end{pmatrix}, \quad \sum_{A} = \begin{pmatrix} O & \\ & S & \\ & I_{k-r-s} \end{pmatrix},$$
$$S_A = \operatorname{diag}(\alpha_{r+1}, \dots, \alpha_{r+s}), \quad S = \operatorname{diag}(\beta_{r+1}, \dots, \beta_{r+s})$$

 $\begin{aligned} &\alpha_i^2+\beta_i^2=1,\ i=r+1,\ldots,r+s,\ 1>\alpha_{r+1}\geq\cdots\geq\alpha_{r+s}>0,\ 0<\beta_{r+1}\leq\cdots\leq\\ &\beta_{r+s}<1,\ k=\mathrm{rank}\ \binom{A}{B^*},\ r=k-\mathrm{rank}\ B,\ s=\mathrm{rank}\ A+\mathrm{rank}\ B-k,\ U\in\mathbb{C}^{m\times m},\\ &V\in\mathbb{C}^{n\times n}\ \mathrm{are\ unitary\ and}\ P\in GL_n. \end{aligned}$

Remark. Proofs, properties of the GSVD and a numerically stable algorithm for the computation of the GSVD can be found in [9]–[10].

Let

(4)
$$P^{-1}XP^{-*} = \begin{pmatrix} X_{11} & X_{12} & X_{13} & X_{14} \\ X_{21} & X_{22} & X_{23} & X_{24} \\ X_{31} & X_{32} & X_{33} & X_{34} \\ X_{41} & X_{42} & X_{43} & X_{44} \end{pmatrix} \begin{pmatrix} r \\ s \\ k-r-s \end{pmatrix},$$

(5)
$$UCV^* = \begin{pmatrix} C_{11} & C_{12} & C_{13} \\ C_{21} & C_{22} & C_{23} \\ C_{31} & C_{32} & C_{33} \end{pmatrix} \begin{matrix} r \\ s \\ m-r-s \end{matrix}$$

$$n-k+r \quad s \quad k-r-s$$

Lemma 4. Consider the matrix equation (1). Let $P^{-1}XP^{-*}$, UCV^* be as in (4) and (5), respectively. Then (1) is consistent if and only if C_{i1} (i = 1, 2, 3) and C_{3j} (j = 2, 3) vanish, in which case the general solution is

(6)
$$X = P \begin{pmatrix} X_{11} & C_{12}S^{-1} & C_{13} & X_{14} \\ X_{21} & S_A^{-1}C_{22}S^{-1} & S_A^{-1}C_{23} & X_{24} \\ X_{31} & X_{32} & X_{33} & X_{34} \\ X_{41} & X_{42} & X_{43} & X_{44} \end{pmatrix} P^*,$$

where X_{i1} , X_{i4} (i = 1, 2, 3, 4), X_{3j} , X_{4j} (j = 2, 3) are arbitrary complex matrices whose orders are given by (4).

PROOF: Obviously, the matrix equation (1) is equivalent to

$$UAPP^{-1}XP^{-*}P^*BV^* = UCV^*.$$

Hence by (2)–(5), (1) is equivalent to

(7)
$$\begin{pmatrix} O & X_{12}S & X_{13} \\ O & S_A X_{22}S & S_A X_{23} \\ O & O & O \end{pmatrix} = \begin{pmatrix} C_{11} & C_{12} & C_{13} \\ C_{21} & C_{22} & C_{23} \\ C_{31} & C_{32} & C_{33} \end{pmatrix}.$$

Accordingly, the lemma follows from (7).

Now we give the main result of the present paper.

Theorem 3. Under the conditions of Lemma 4, the matrix equation (1) has a Re-nnd solution if and only if C_{i1} (i = 1, 2, 3) and C_{3j} (j = 2, 3) vanish, and $S_A^{-1}C_{22}S^{-1}$ is Re-nnd. In that case, the general Re-nnd solution of (1) is

(8)
$$X = P \begin{pmatrix} M & N \\ -N^* + T^*(M + M^*) & D + T^*MT \end{pmatrix} P^*,$$

where

$$M = \begin{pmatrix} D_2 + T_2^* (S_A^{-1} C_{22} S^{-1}) T_2 & C_{12} S^{-1} & C_{13} \\ F & S_A^{-1} C_{22} S^{-1} & S_A^{-1} C_{23} \\ X_{31} & G & D_1 + T_1^* S_A^{-1} C_{22} S^{-1} T_1 \end{pmatrix},$$

$$\begin{array}{ll} \text{with} & F = -S^{-1}C_{12}^* + (S_A^{-1}C_{22}S^{-1} + S^{-1}C_{22}^*S_A^{-1})T_2, \\ & G = -C_{23}^*S_A^{-1} + T_1^*(S_A^{-1}C_{22}S^{-1} + S^{-1}C_{22}^*S_A^{-1}), \\ X_{31} \in \{X_{31} \in \mathbb{C}^{(k-r-s)\times r} \mid M \in E^k\}, \ D_1 \in E^{k-r-s}, \ D_2 \in E^r, \ D \in E^{n-k}, \\ T_1 \in \mathbb{C}^{s \times (k-r-s)}, \ T_2 \in \mathbb{C}^{s \times r}, \ T \in \mathbb{C}^{k \times (n-k)}, \ N \in \mathbb{C}^{k \times (n-k)} \ \text{are all arbitrary}. \end{array}$$

PROOF: If the matrix equation (1) has a solution $X \in E^n$, then by Lemma 4 C_{i1} (i = 1, 2, 3) and C_{3j} (j = 2, 3) vanish and X has the form of (6). Hence

$$\begin{pmatrix} X_{11} & C_{12}S^{-1} & C_{13} & \vdots & X_{14} \\ X_{21} & S_A^{-1}C_{22}S^{-1} & S_A^{-1}C_{23} & \vdots & X_{24} \\ X_{31} & X_{32} & X_{33} & \vdots & X_{34} \\ \vdots & \vdots & \vdots & \vdots \\ X_{41} & X_{42} & X_{43} & \vdots & X_{44} \end{pmatrix} \xrightarrow{\text{def.}} \begin{pmatrix} M & \vdots & N \\ \vdots & N \\ \vdots & \vdots & \vdots \\ N_1 & \vdots & X_{44} \end{pmatrix} \in E^n.$$

By Theorem 1, M and

$$(9) X_{44} - T^*MT \stackrel{\text{def.}}{=\!=\!=} D$$

are all Re-nnd where T is an arbitrary solution of the matrix equation

$$(10) (M+M^*)X = N_1^* + N.$$

By Theorem 2,

$$\begin{pmatrix} X_{11} & C_{12}S^{-1} \\ X_{21} & S_A^{-1}C_{22}S^{-1} \end{pmatrix} \text{ and } \begin{pmatrix} S_A^{-1}C_{22}S^{-1} & S_A^{-1}C_{23} \\ X_{32} & X_{33} \end{pmatrix}$$

are all Re-nnd. Hence by Theorem 1, on the one hand, both $S_A^{-1}C_{22}S^{-1}$ and

(11)
$$X_{11} - T_2^* S_A^{-1} C_{22} S^{-1} T_2 \stackrel{\text{def.}}{=} D_2$$

are all Re-nnd where T_2 is an arbitrary solution of the matrix equation

(12)
$$(S_A^{-1}C_{22}S^{-1} + S^{-1}C_{22}^*S_A^{-1})X = S^{-1}C_{12}^* + X_{21}.$$

On the other hand,

(13)
$$X_{33} - T_1^* S_A^{-1} C_{22} S^{-1} T_1 \stackrel{\text{def.}}{===} D_1$$

is also Re-nnd where T_1 is any solution of the matrix equation

(14)
$$(S_A^{-1}C_{22}S^{-1} + S^{-1}C_{22}^*S_A^{-1})X = S_A^{-1}C_{23} + X_{32}.$$

Consequently, by (10)–(14), X has the form of (8).

Conversely, assume C_{i1} (i=1,2,3) and C_{3j} (j=2,3) vanish and $S_A^{-1}C_{22}S^{-1}$ is Re-nnd. Then by Theorem 1 and Theorem 2, there exists $X_{31} \in \mathbb{C}^{(k-r-s)\times r}$ such that

$$\begin{pmatrix} M & N \\ -N^* + T^*(M+M^*) & D + T^*MT \end{pmatrix}$$

is Re-nnd. Hence the matrix X of type (8) is Re-nnd. It is easy to verify that the matrix X of type (8) is a solution of the matrix equation (1).

References

- [1] Wu L., Cain B., The Re-nonnegative definite solutions to matrix inverse problem AX = B, Linear Algebra Appl. 236 (1996), 137–146.
- [2] Khatri C.G., Mitra S.K., Hermitian and nonnegative definite solutions of linear matrix equations, SIAM J. Appl. Math. 31.4 (1976), 579–585.

- [3] Chu K.E., Singular value and general singular value decompositions and the solution of linear matrix equation, Linear Algebra Appl. 88/89 (1987), 83–98.
- [4] Porter A.D., Mousouris N., Ranked solutions of AXC = B and AX = B, Linear Algebra Appl. 24 (1979), 217–224.
- [5] Dai H., On the symmetric solution of linear matrix equations, Linear Algebra Appl. 131 (1990), 1–7.
- [6] Wang Q.W., The metapositive definite self-conjugate solutions of the matrix equation AXB = C over a skew field, Chinese Quarterly J. Math. 3 (1995), 42–51.
- Wang Q.W., The matrix equation AXB = C over an arbitrary skew field, Chinese Quarterly J. Math. 4 (1996), 1–5.
- [8] Wang Q.W., Skewpositive semidefinite solutions to the quaternion matrix equation AXB = C, Far East. J. Math. Sci., to appear.
- [9] Paige C.C., Saunders M.A., Towards a generalized singular value decomposition, SIAM J. Numer. Anal. 18 (1981), 398–405.
- [10] Stewart G.W., Computing the CS-decomposition of a partitioned orthogonal matrix, Numer. Math. 40 (1982), 297–306.

DEPARTMENT OF MATHEMATICS, CHANGWEI TEACHERS COLLEGE, WEIFANG 261043, SHANDONG, P.R. CHINA

DEPARTMENT OF MATHEMATICS AND PHYSICS, SHANDONG UNIVERSITY OF TECHNOLOGY, JINAN 250061, SHANDONG, P.R. CHINA

(Received December 18, 1996, revised August 5, 1997)